

Sparsity Theory for Dense Graphs

Nikolas Mählmann

Sparsity - Graphs and Algorithms 01.02.2024

The Model Checking Problem

Problem: Given a graph G and a formula φ in a logic $\mathcal{L} \in \{FO, MSO\}$, decide $G \models \varphi$.

Examples:

- FO: distance- r red blue independent/dominating set of size k
- MSO: 3-colorability, SAT

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Question: On which classes graph is model checking fixed-parameter tractable, i.e., solvable in time $f(\varphi) \cdot n^c$?

Monadic Second-Order Logic

MSO Model Checking

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Treedepth, treewidth, minors, bounded expansion, nowhere denseness, etc.
are all measures for monotone graph classes.

To handle dense graphs we need **complexity measures for hereditary graph classes!**

Classes of Bounded Cliquewidth

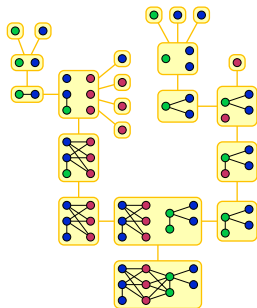


figure by David Eppstein under CC0

Labeled graphs of cliquewidth k are constructed using the following operations:

1. Creating a vertex with label $i \in [k]$.

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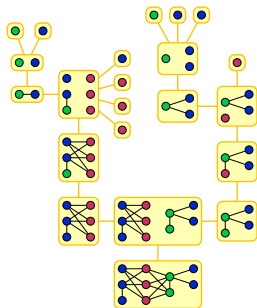


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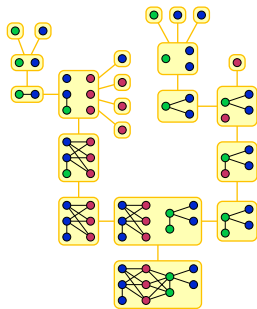


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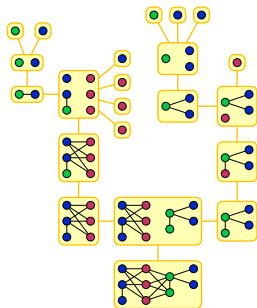


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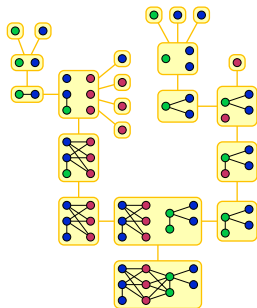


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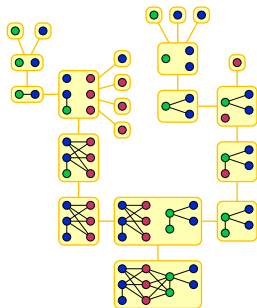


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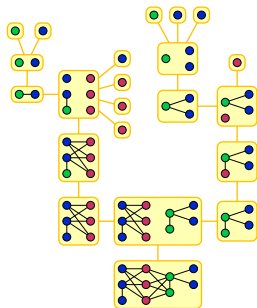


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Theorem [Courcelle, Makowsky, Rotics, 2000] [Oum, Seymour, 2006]

Every class of bounded cliquewidth admits MSO model checking in time $f(\varphi) \cdot n^3$.

First-Order Logic

Nowhere Dense Classes of Graphs

Definition [Něsetřil, Ossona de Mendez, 2011]

A class \mathcal{C} is *nowhere dense*, if for every r there exists k such \mathcal{C} that does not contain the r -subdivided clique of size k as a subgraph.

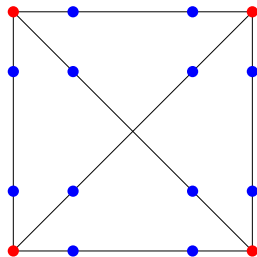


Figure: The 2-subdivided K_4 .

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Generalizes many notions of sparsity such as:
bounded degree, bounded treewidth, planarity,
excluding a minor, ...

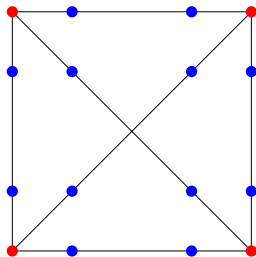


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excluding a minor, ...

Theorem [Grohe, Kreutzer, Siebertz, 2014]

Let \mathcal{C} be a *monotone* class of graphs. If \mathcal{C} is nowhere dense, then FO model checking on \mathcal{C} can be done in time $f(\varphi, \varepsilon) \cdot n^{1+\varepsilon}$ for every $\varepsilon > 0$. Otherwise it is AW[*]-hard.

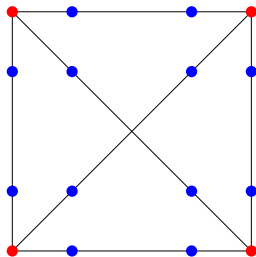


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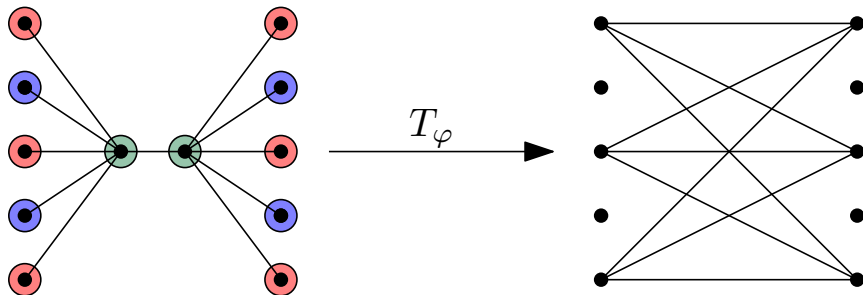
How to produce well behaved hereditary classes from sparse classes?

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How to produce well behaved hereditary classes from sparse classes?

Transductions $\hat{=}$ coloring + interpreting + taking an induced subgraph



$$\varphi(x, y) := \text{Red}(x) \wedge \text{Red}(y) \wedge \text{dist}(x, y) = 3$$

Structural Sparsity and Monadic Stability

Definition

A class \mathcal{C} is *structurally nowhere dense*, if there exists a transduction T and a nowhere dense class \mathcal{D} such that $\mathcal{C} \subseteq T(\mathcal{D})$.

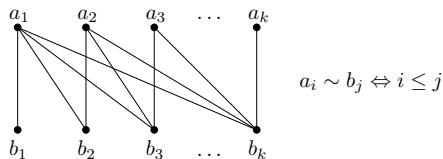
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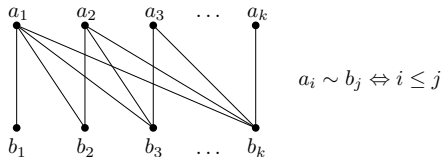
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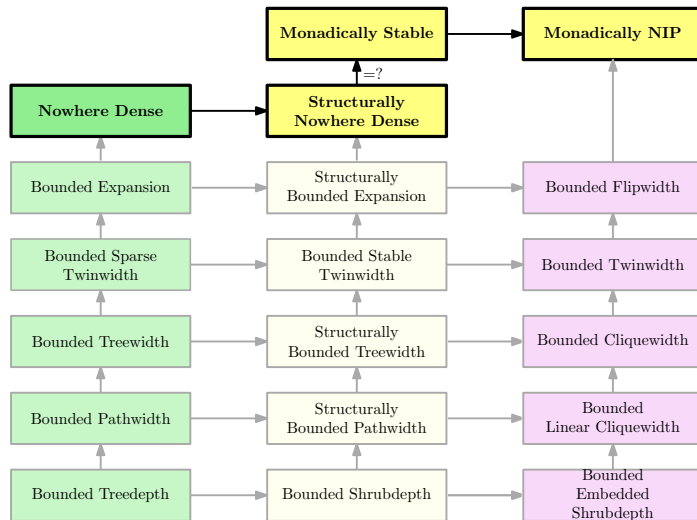
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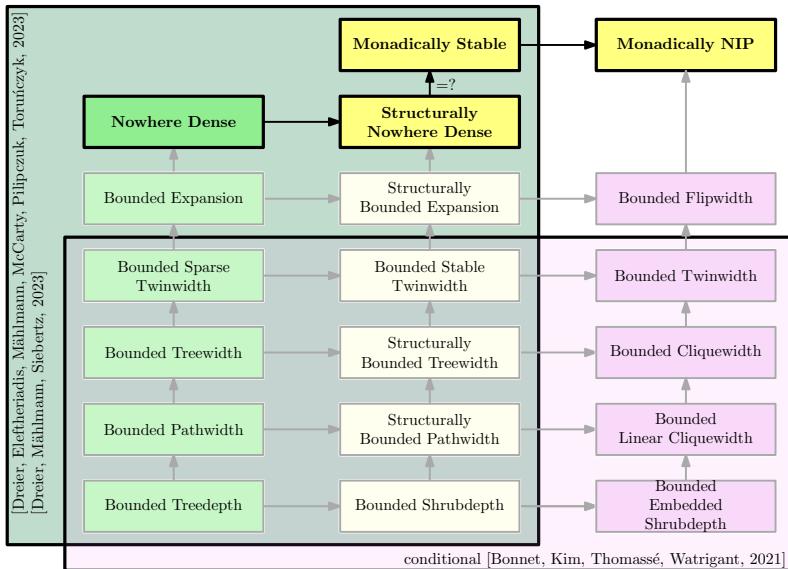
Definition

A class is *monadically NIP*, if it does not transduce the class of all graphs.

Map of the Universe



Map of the Universe



Tractable Classes

Theorem [Grohe, Kreutzer, Siebertz, 2014]

Let \mathcal{C} be a **monotone** class of graphs.

\mathcal{C} admits fpt FO model checking if and only if \mathcal{C} is **nowhere dense**.

Theorem [Dreier, Eleftheriadis, Mählmann, McCarty, Pilipczuk, Toruńczyk, 2023+]

Let \mathcal{C} be a **hereditary and orderless** class of graphs.

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Theorem [Bonnet, Giocanti, Ossona de Mendez, Simon, Thomassé, Toruńczyk, 2022]

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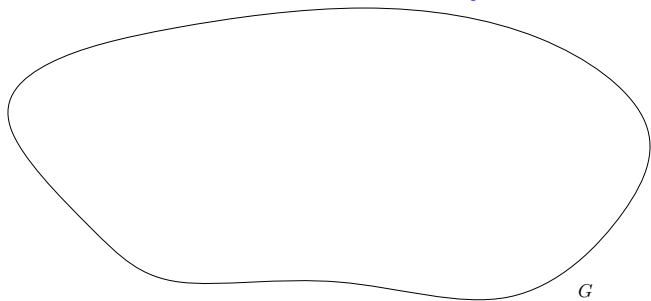
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Agenda

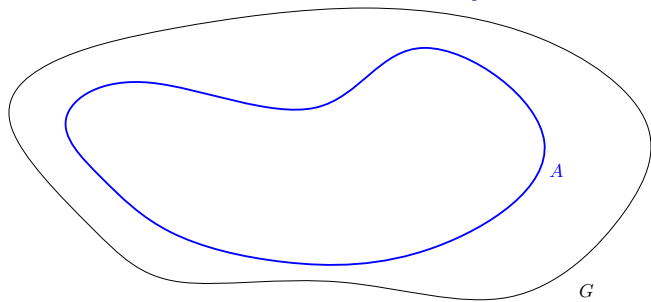
I will present some of our research results:

1. Characterizations of monadically stable and monadically NIP classes.
2. A game for monadically stable graph classes.
3. FO model checking for monadically stable graph classes.

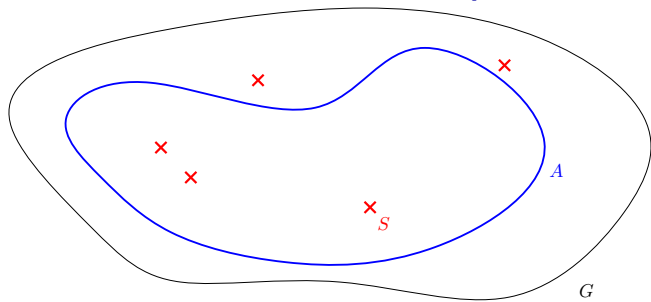
Characterizing Nowhere Denseness: Uniform Quasi-Wideness



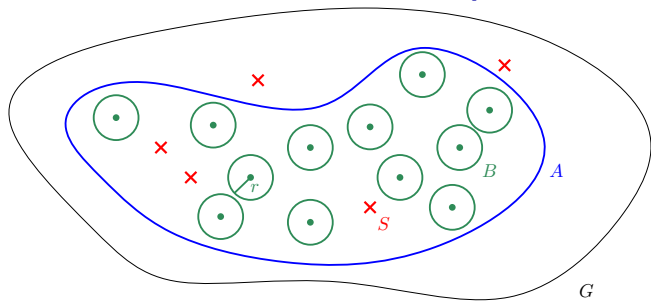
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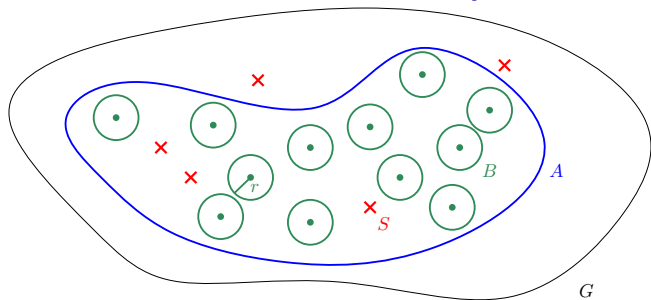
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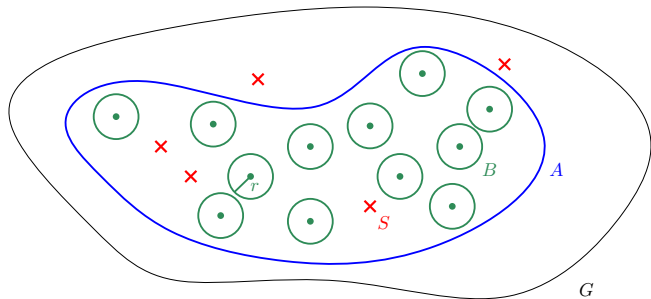
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Uniform Quasi-Wideness (slightly informal)

A class \mathcal{C} is *uniformly quasi-wide* if for every radius r , in every large set A we find a still large set B that is r -independent after removing a set S of constantly many vertices.

Characterizing Nowhere Denseness: Uniform Quasi-Wideness



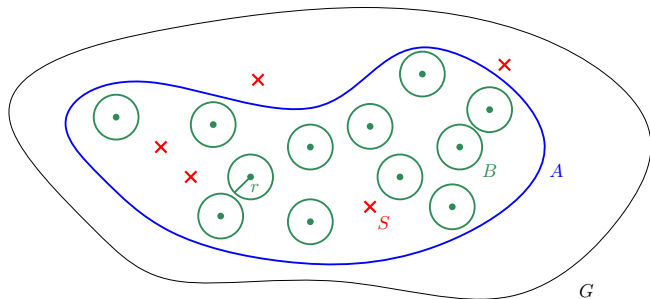
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Formally:

$\forall r \exists s_r \in \mathbb{N}, N_r : \mathbb{N} \rightarrow \mathbb{N}$ s.t. $\forall G \in \mathcal{C}, A \subseteq V(G)$ with $|A| \geq N_r(m)$
 $\exists B \subseteq A, S \subseteq V(G)$ with $|B| \geq m, |S| \leq s_r$ s.t. B is r -independent in $G - S$.

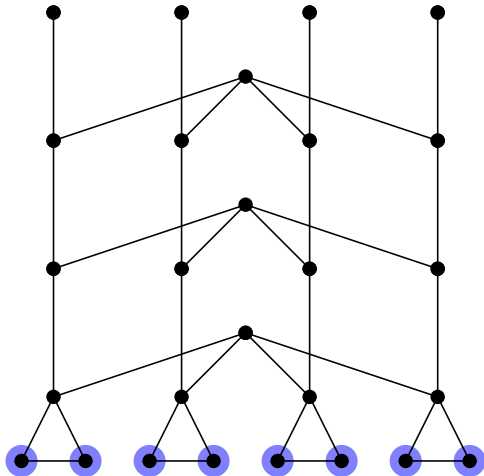
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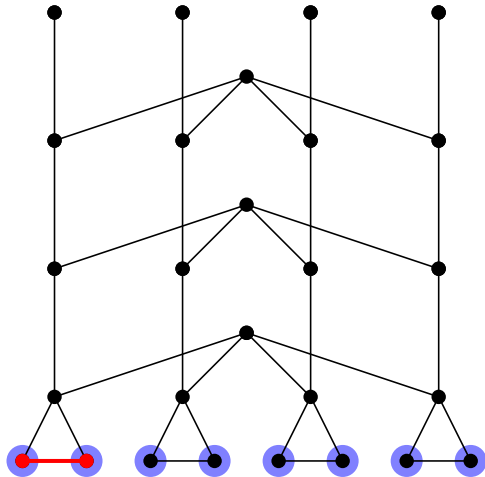
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Uniform Quasi-Wideness: Example

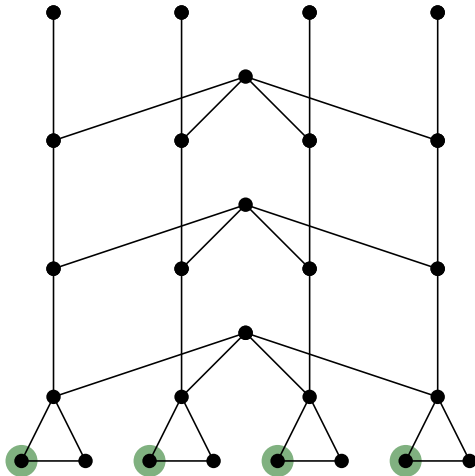


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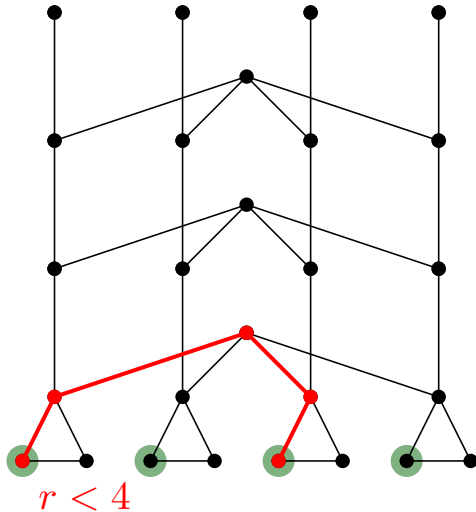


$$r < 1$$

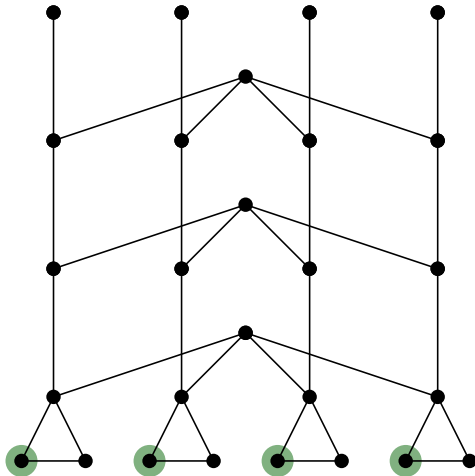
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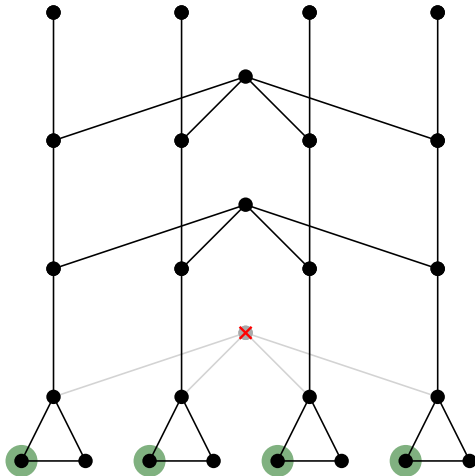
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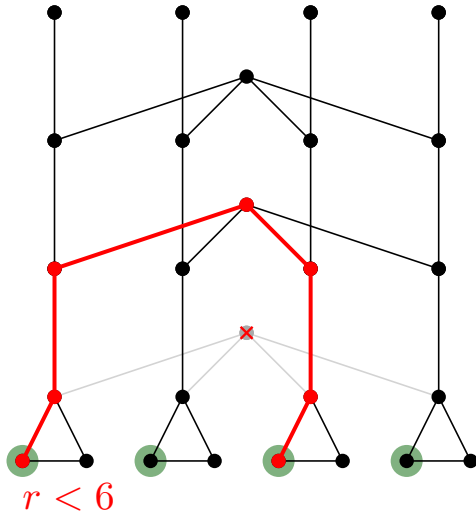
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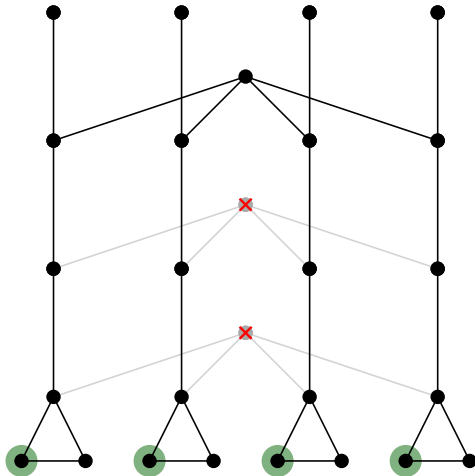
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Flips

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Question: Similar **combinatorial characterizations** for monadic stability/NIP?

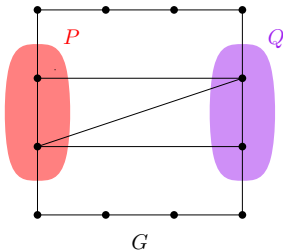
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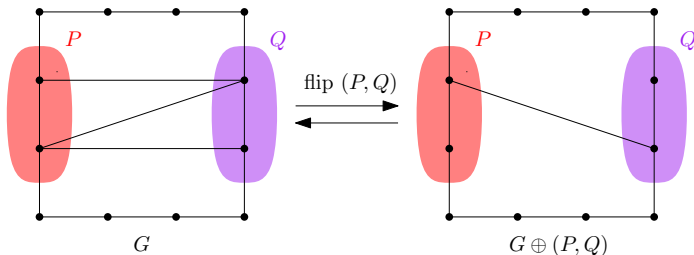
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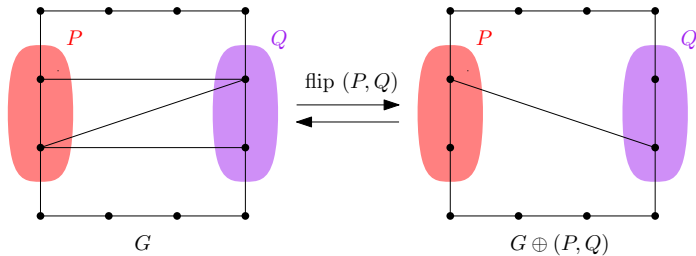
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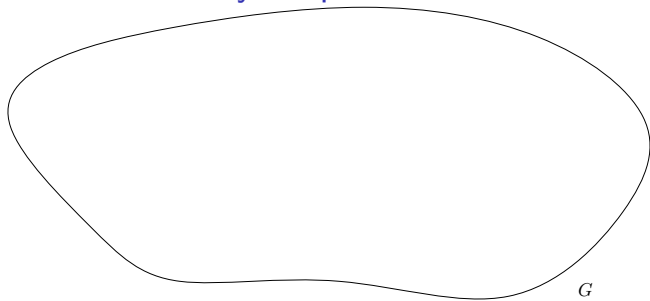
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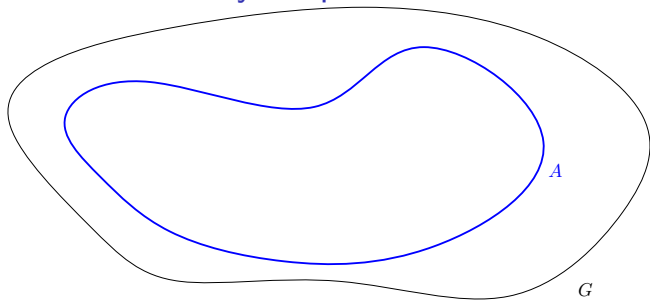


$$G \models E(u, v) \quad \Leftrightarrow \quad G \oplus (P, Q) \models E(u, v) \text{ XOR } (P(u) \wedge Q(v) \vee P(v) \wedge Q(u))$$

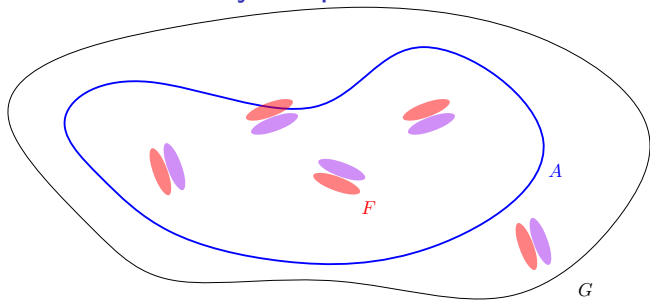
Characterizing Monadic Stability: Flip-Flatness



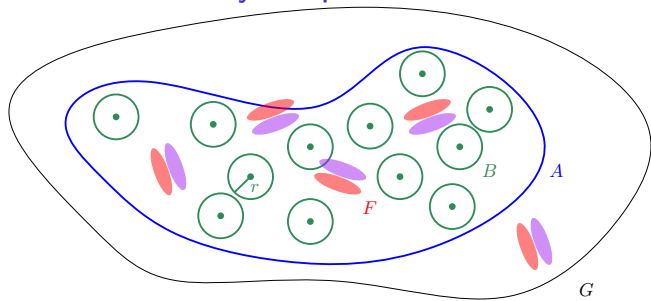
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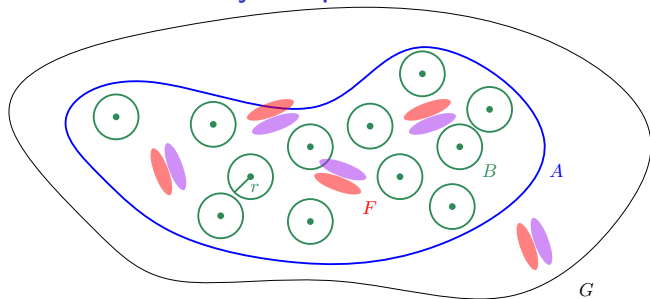
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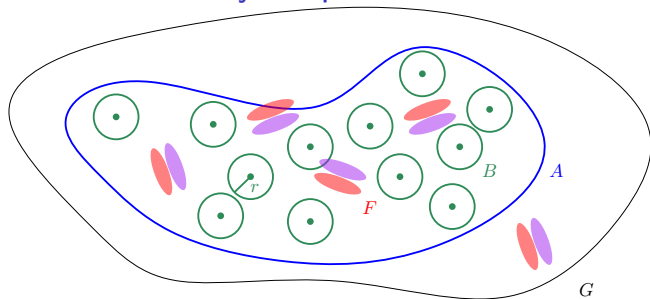
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Flip-Flatness (slightly informal) [Gajarský, Kreutzer]

A class \mathcal{C} is *flip-flat* if for every radius r , in every large set S we find a still large set A that is r -independent after performing a set F of constantly many flips.

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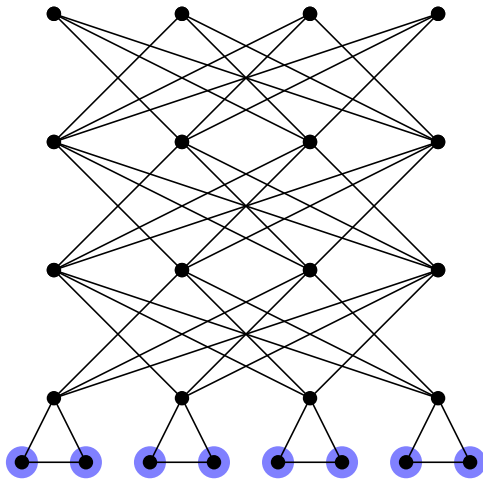
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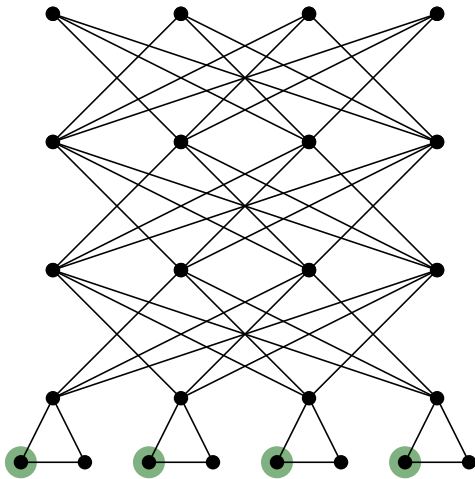
Theorem [Dreier, Mählmann, Siebertz, Toruńczyk, 2022]

A class \mathcal{C} is flip-flat if and only if it is monadically stable.

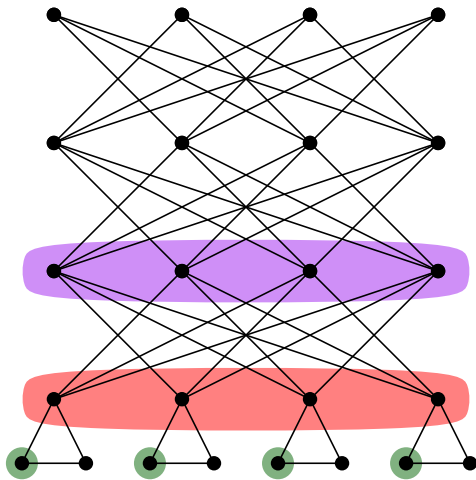
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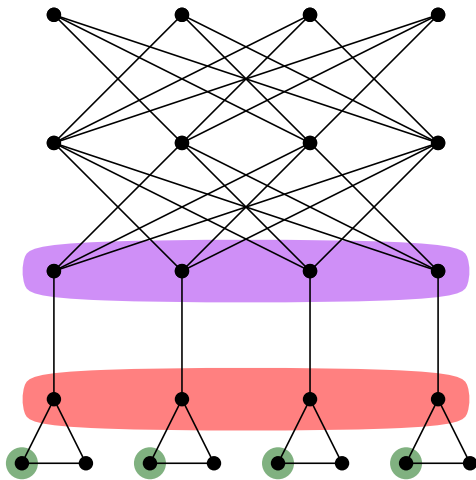
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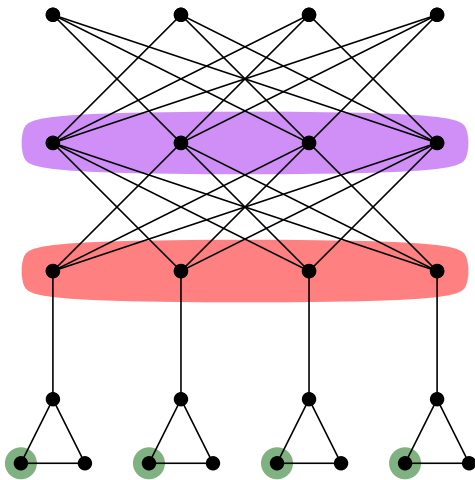
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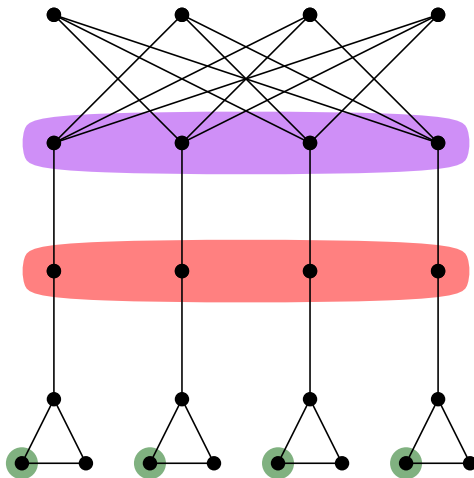
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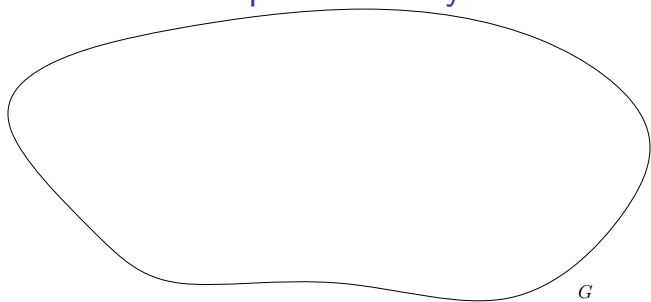
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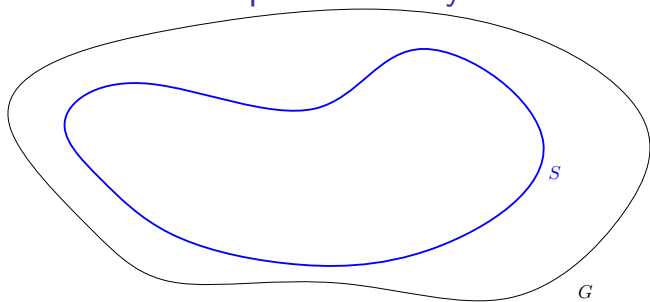
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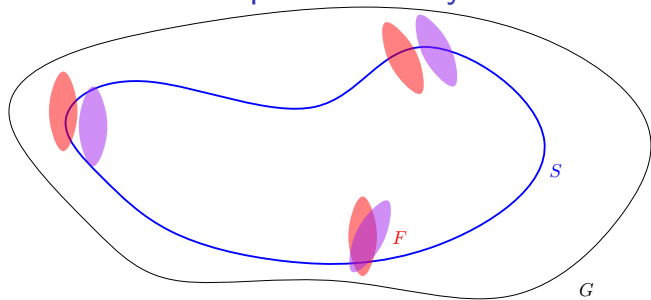
Characterizing Monadic NIP: Flip-Breakability



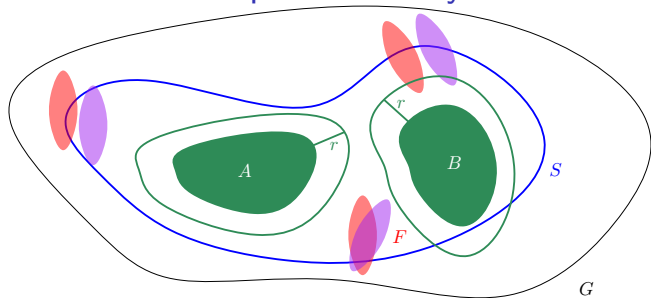
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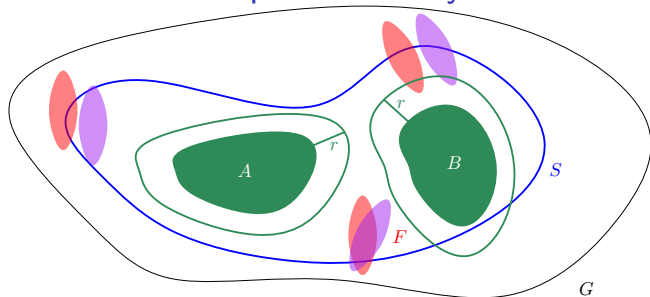
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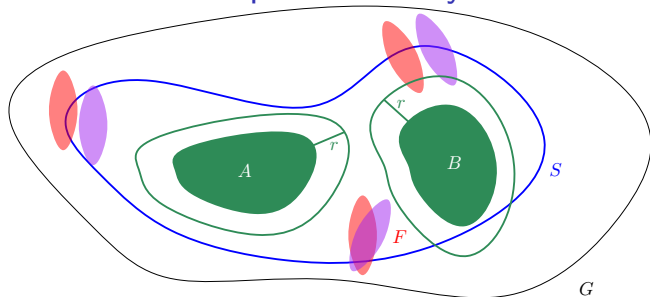
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Flip-Breakability (slightly informal)

A class \mathcal{C} is *flip-breakable* if for every radius r , in every large set S we find two large sets A and B that and a flip F of bounded size such that $N_{G \oplus F}^r(A) \cap N_{G \oplus F}^r(B) = \emptyset$.

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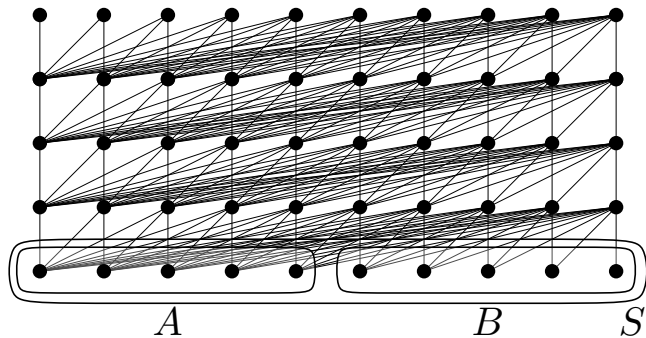
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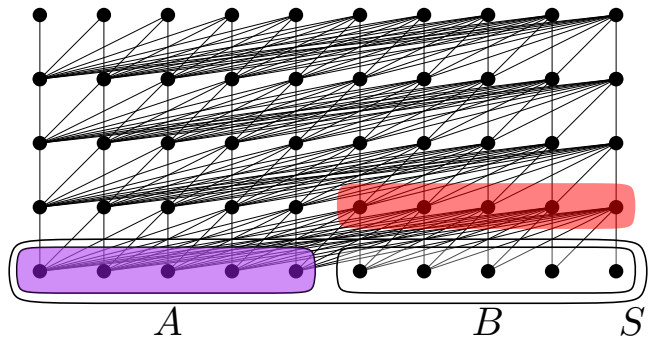
Theorem [Dreier, Mählmann, Toruńczyk]

A class \mathcal{C} is flip-breakable if and only if it is monadically NIP.

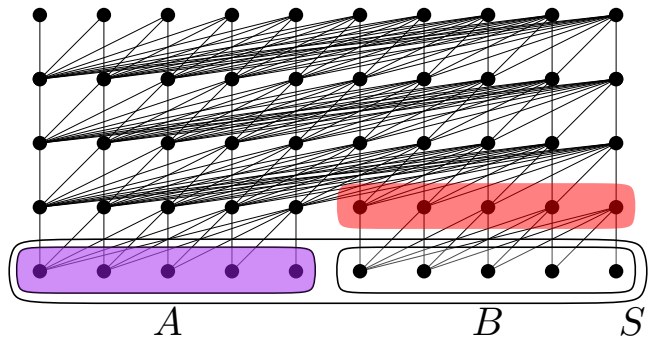
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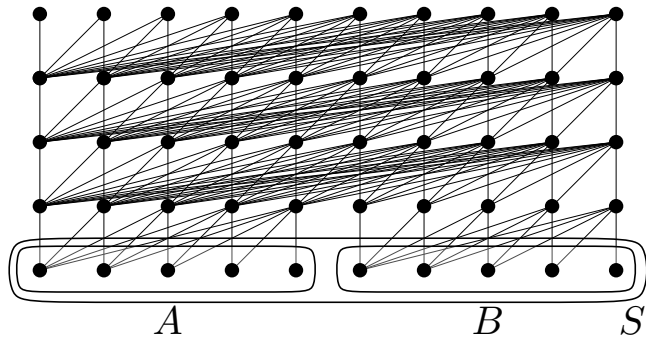
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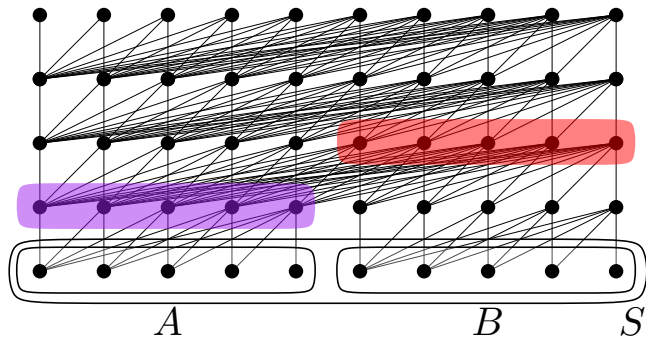
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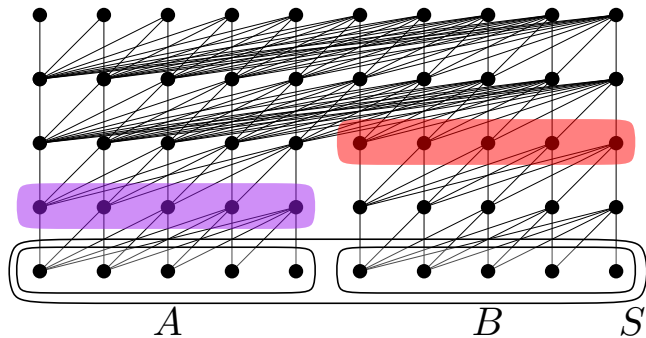
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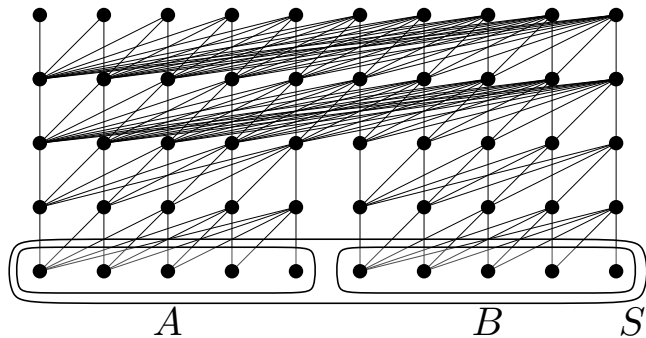
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Roadmap: FO Model Checking for Monadically Stable Classes

flip-flatness \rightarrow flipper game \rightarrow model checking

Monadic Stability \Rightarrow Flip-Flatness: $r = 1$

We prove flip-flatness by induction on r . For $r = 1$ we use Ramsey's theorem.

Case 1: A contains a large independent set.



$\rightarrow B$ is distance-1 independent without performing any flips.

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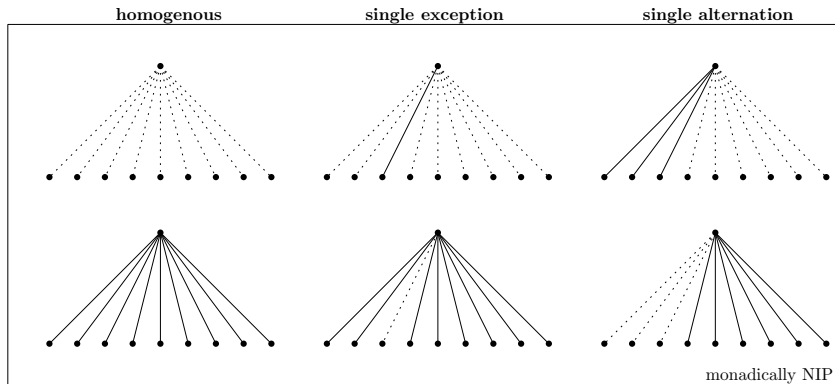
Case 2: A contains a large clique.



$\rightarrow \text{flip } (B, B)$. This is the same as complementing the edges in B .

Indiscernibles

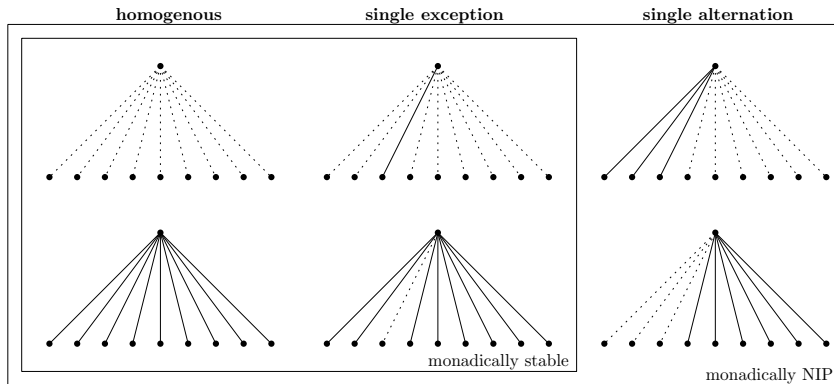
Every long sequence of vertices contains a still long subsequence that is *indiscernible*.
In a monadically NIP class every vertex is connected to an indiscernible sequence in one of the following patterns:



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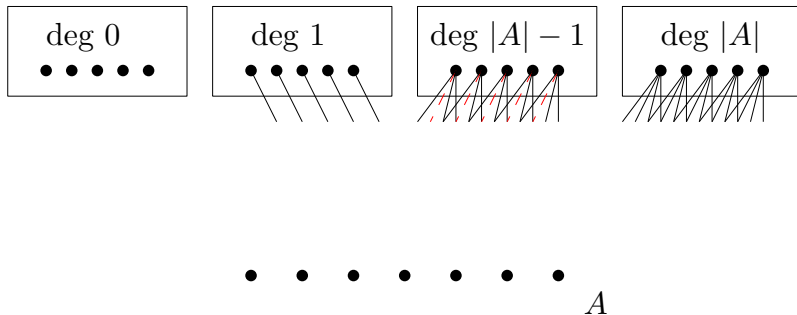
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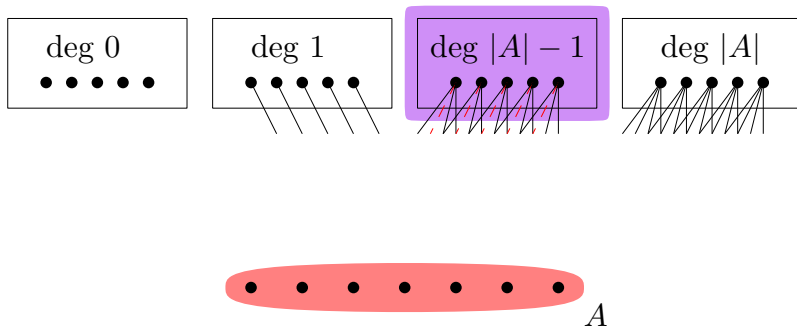


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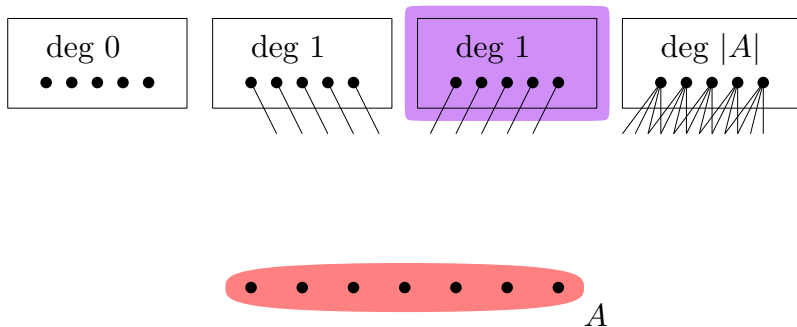
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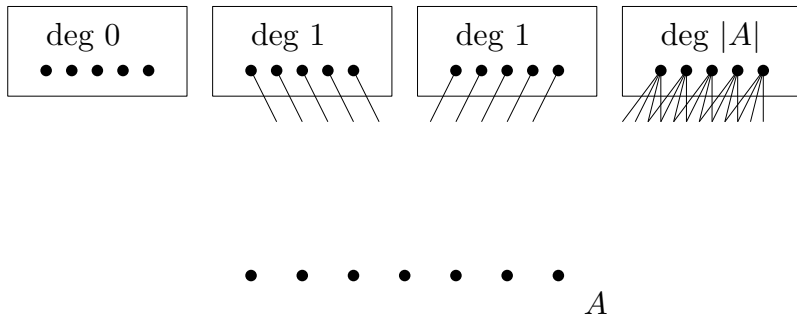
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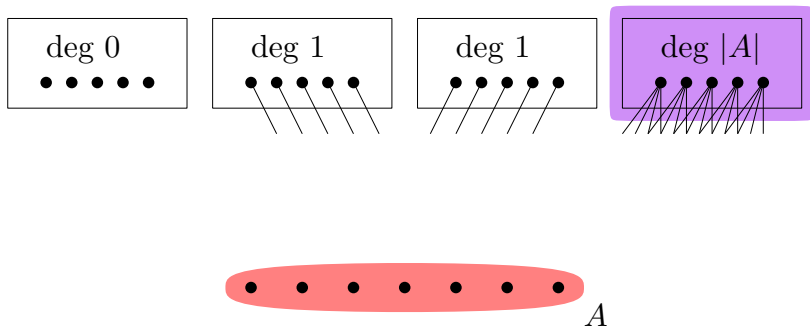
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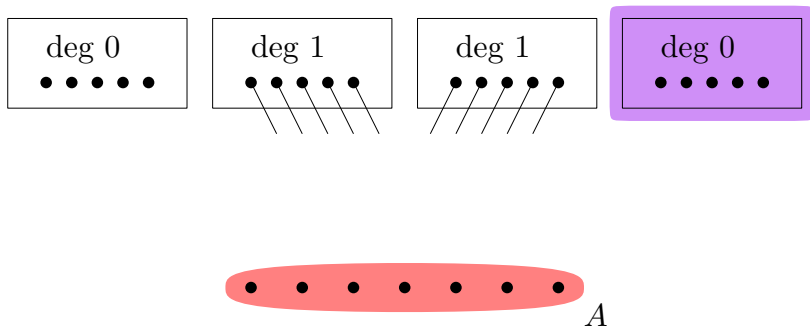
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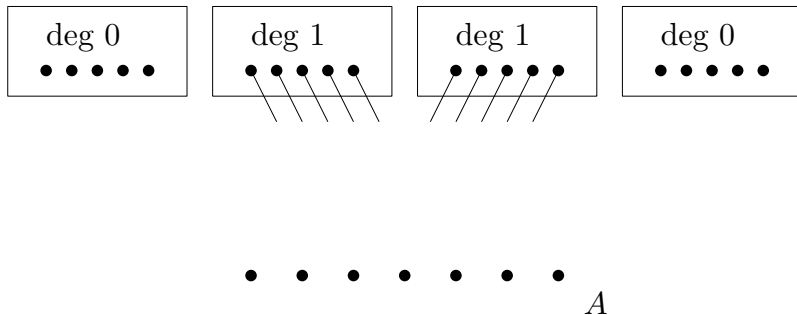
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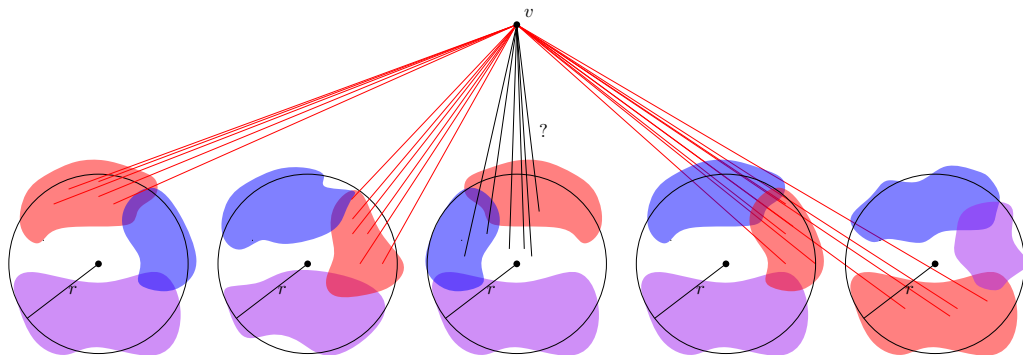


Monadic Stability \Rightarrow Flip-Flatness: $r = 2$



Monadic Stability \Rightarrow Flip-Flatness: $r \geq 3$

If \mathcal{C} is monadically stable, then every large sequence of disjoint r -balls contains a large subsequence that can be colored by a bounded number of colors such that the neighborhood of every vertex is described by a single colors as follows:



Roadmap: FO Model Checking for Monadically Stable Classes

flip-flatness $\checkmark \rightarrow$ flipper game \rightarrow model checking

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The radius- r Splitter game is played on a graph G_1 . In round i

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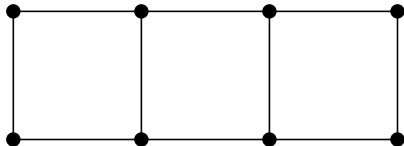
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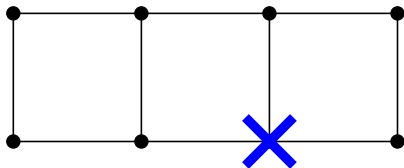
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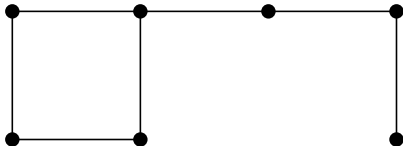
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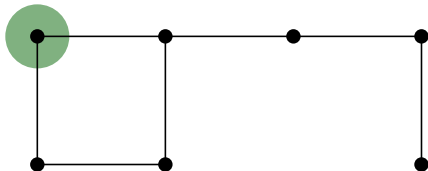
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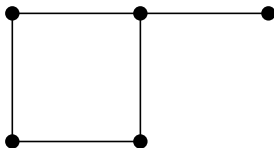
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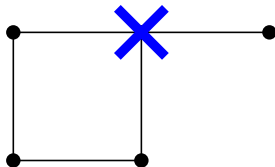
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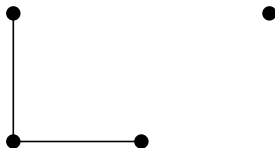
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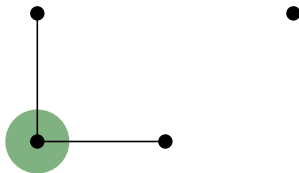
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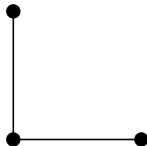
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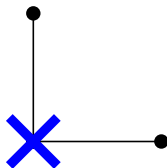
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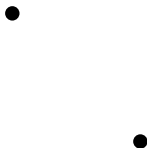
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Theorem [Grohe, Kreutzer, Siebertz, 2013]

A class of graphs \mathcal{C} is nowhere dense \Leftrightarrow

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Question: Can we find a similar **game characterization** for monadic stability?

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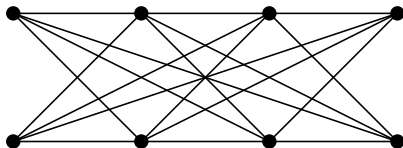
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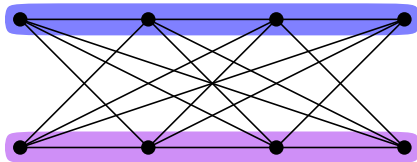
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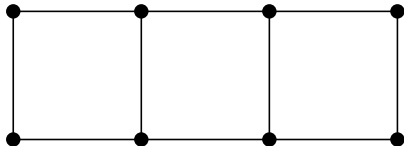
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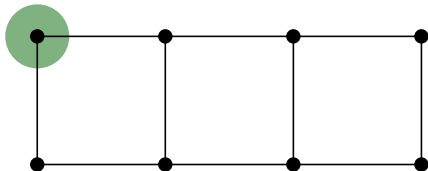
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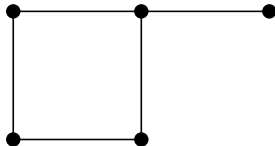
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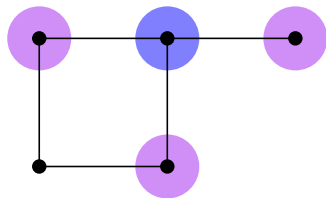
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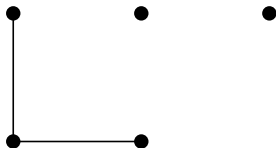
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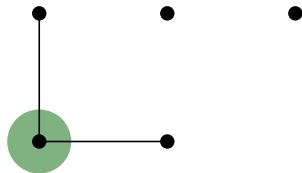
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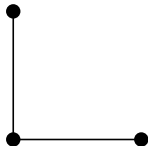
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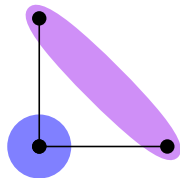
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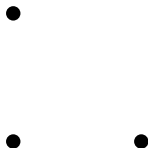
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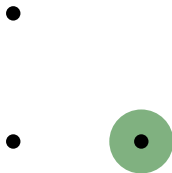
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The Flipper Game in Monadically Stable Classes

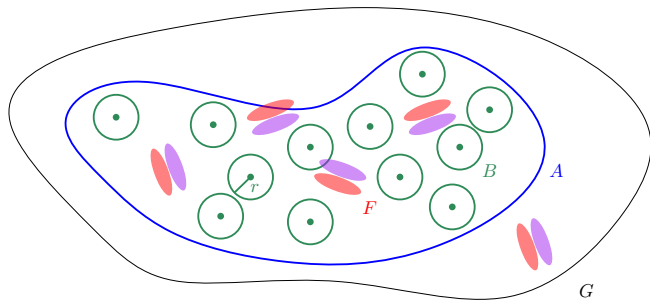
Theorem [Gajarský, Möhlmann, McCarty, Ohlmann, Pilipczuk, Przybyszewski, Siebertz, Sokołowski, Toruńczyk, 2023]

A class of graphs \mathcal{C} is monadically stable \Leftrightarrow

$\forall r \exists \ell$ such that Flipper wins the radius- r game on all graphs from \mathcal{C} in ℓ rounds.

Flippers moves are computable in time $\mathcal{O}_{\mathcal{C},r}(n^2)$.

Flip-Flatness



Definition (slightly informal) [Gajarský, Kreutzer]

A class \mathcal{C} is *flip-flat* if for every radius r , in every large set A we find a still large set B that is r -independent after performing a constant number of flips.

Theorem [Dreier, Möhlmann, Siebertz, Toruńczyk, 2023]

A class \mathcal{C} is flip-flat if and only if it is monadically stable.

Monadic Stability \Rightarrow Flipper Wins - Proof Idea

Let $A = a_1, a_2, a_3, \dots$ be the vertices played by Connector.

If the game continues long enough, we can apply flip-flatness to find a set $B \subseteq A$ which is $2r$ -independent after applying constantly many flips F .

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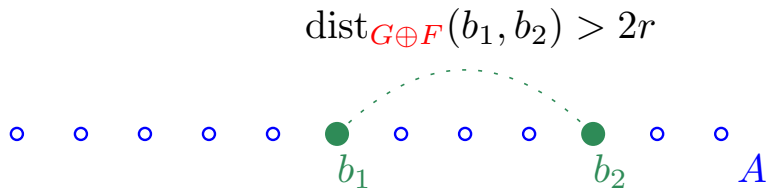
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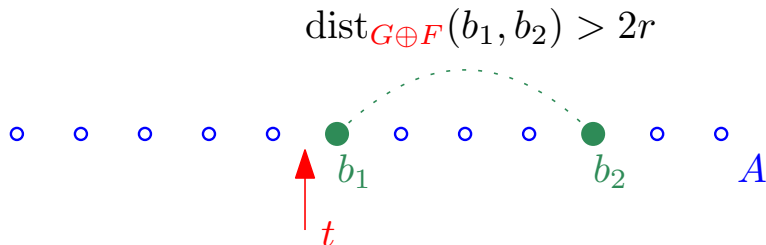
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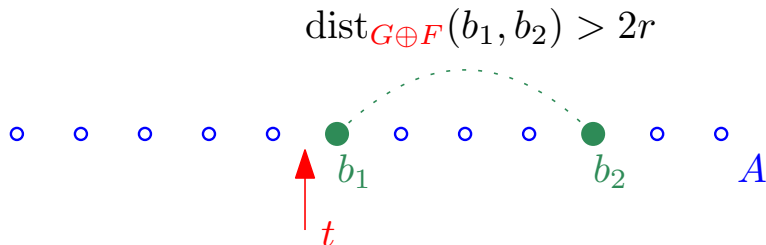
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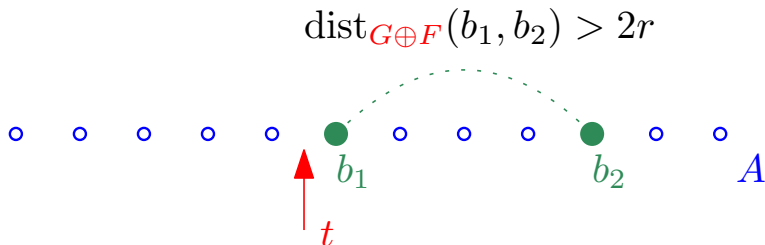


If Flipper had played the flip F at time t then only one of b_1 and b_2 could have survived in the graph.

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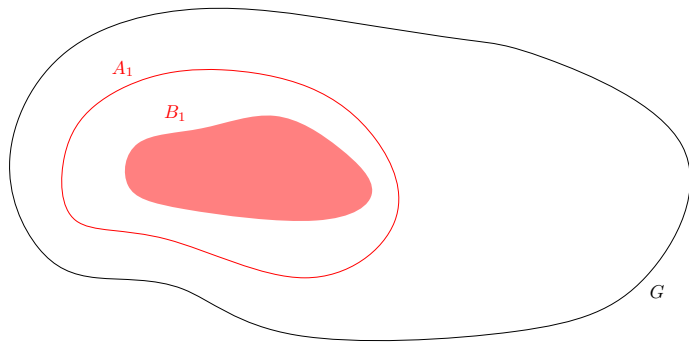
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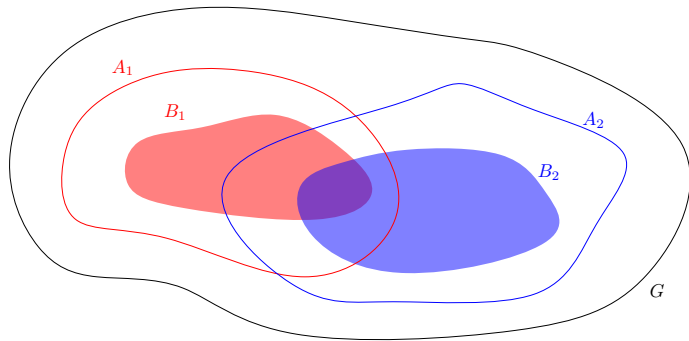
Problem: Flipper does not know A at time t .

Predictable Flip-Flatness



$$\text{ff}(A_1) = (B_1, F_1)$$

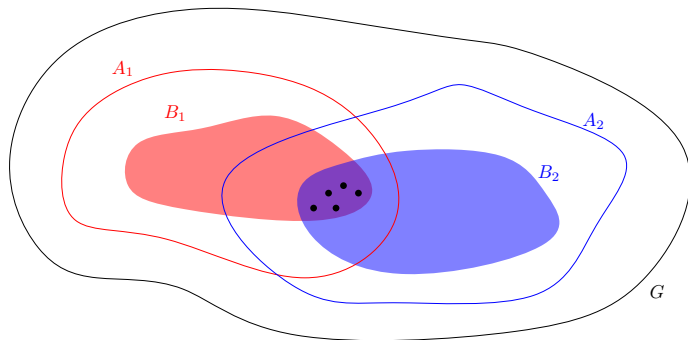
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Predictable Flip-Flatness



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$$|B_1 \cap B_2| \geq 5 \quad \Rightarrow \quad F_1 = F_2$$

$F_1 = F_2$ are computable from a five-element subset of $B_1 \cap B_2$ in time $\mathcal{O}(n^2)$.

Flippers Winning Strategy

For every 5 element subset P of Connectors previous moves:

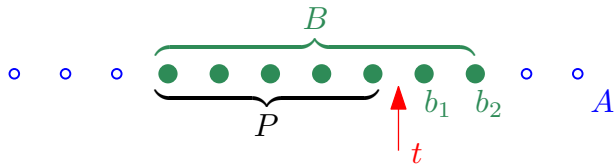
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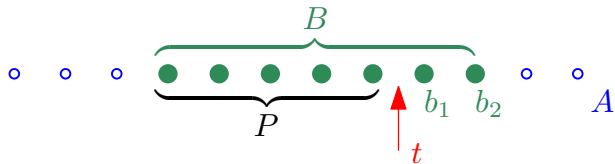


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At time t , P was considered as a subset of Connectors previous moves.

B was flipped $2r$ -independent and only one of b_1, b_2 survived. **Contradiction!**

Roadmap: FO Model Checking for Monadically Stable Classes

flip-flatness $\checkmark \rightarrow$ flipper game $\checkmark \rightarrow$ model checking

Towards a Recursive Model Checking Algorithm

Goal: Decide whether $G \models \varphi$.

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How do we localize? What radius r do we play the Flipper game with?

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For every graph G and $\{U_1, \dots, U_t\}$ -guarded formula ψ we have

$$G \models \psi \iff G[U_1 \cup \dots \cup U_t] \models \psi.$$

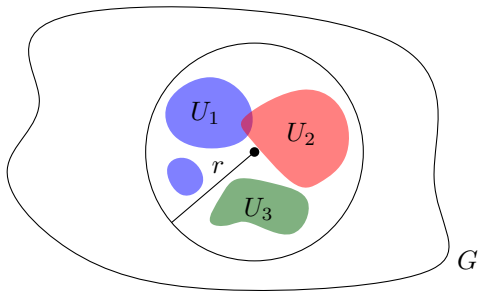
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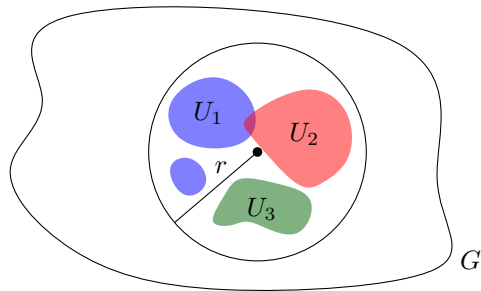
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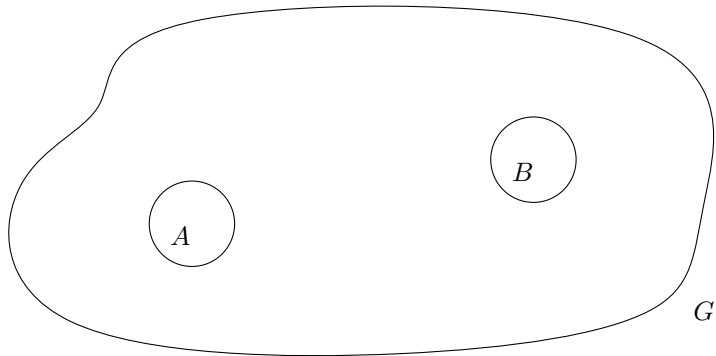
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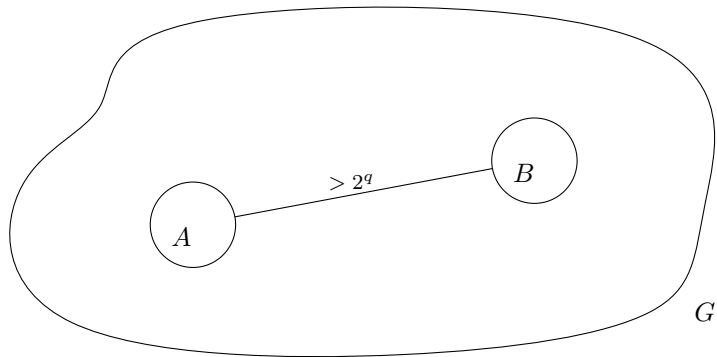
Goal: efficiently compute ψ s.t.

1. ψ is equivalent to φ on G .
2. ψ is a BC of formulas, each guarded by a family of bounded radius in G .

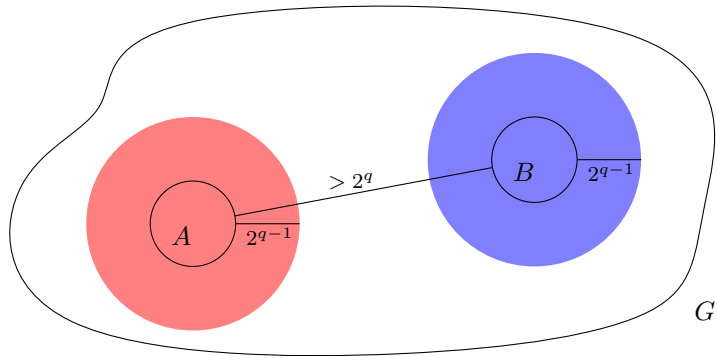
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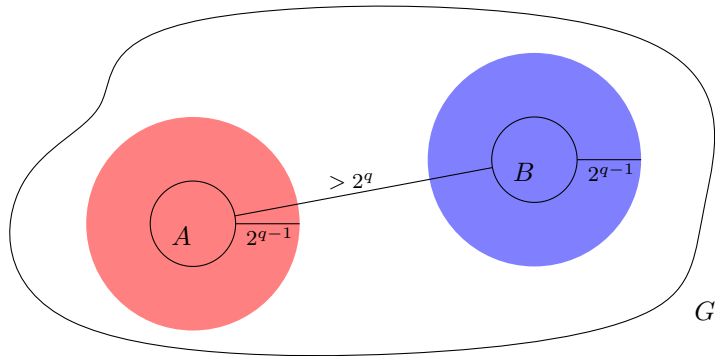
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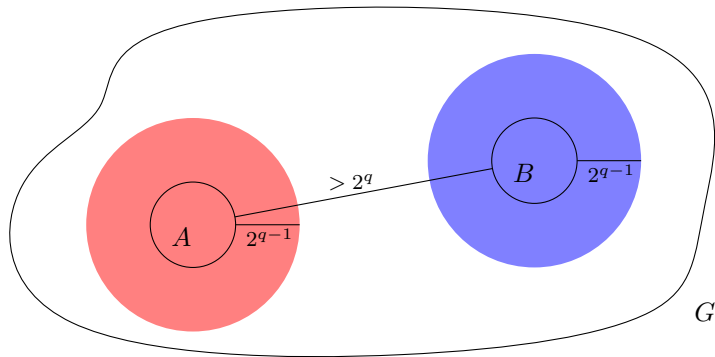


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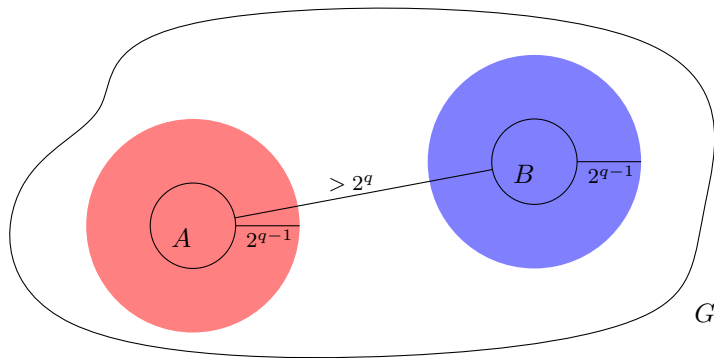
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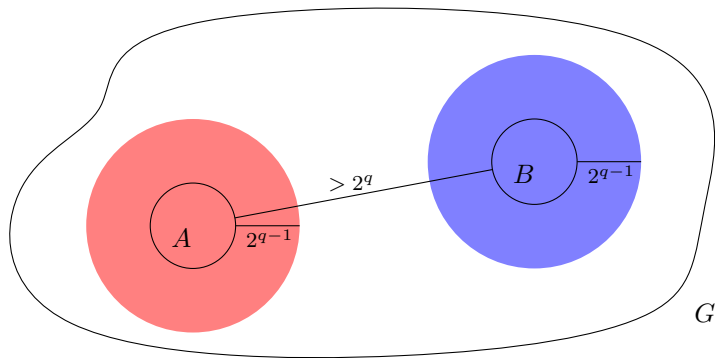


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The proof uses a local variant of Ehrenfeucht-Fraïssé games.

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For multiple quantifiers: extend to parameters and argue by induction ✓

Recursion Tree

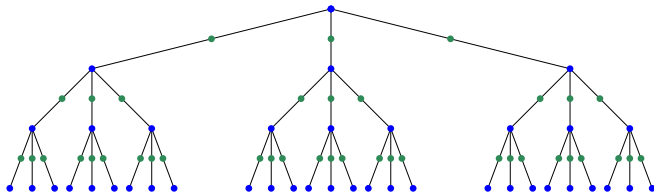
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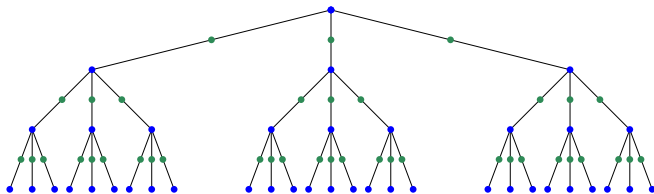


By monadic stability the depth of the recursion tree is bounded by $f(q)$.

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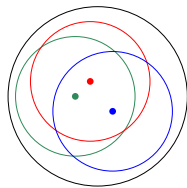
However the branching degree is n . This gives an $\mathcal{O}(n^{f(q)})$ algorithm.

This is worse than the naive $\mathcal{O}(n^q)$ algorithm!

Neighborhood Covers

Recurring into each 2^q -neighborhood is too expensive!

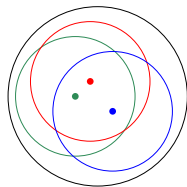
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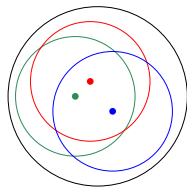
A family of sets \mathcal{X} is a *neighborhood cover* with radius r , spread s , and degree d if

- each r -neighborhood of G is fully contained in one cluster $X \in \mathcal{X}$,
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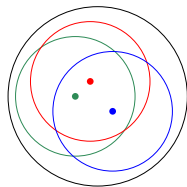
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The size of the clusters of a sparse neighborhood cover sum up to $g(r, \varepsilon) \cdot n^{1+\varepsilon}$.

Resulting size of the recursion tree: $n^{((1+\varepsilon)^{f(q)})}$; by choosing ε small enough: $n^{1+\varepsilon'}$.

Model Checking in Monadically Stable Classes

Theorem [Dreier, Mählmann, Siebertz, 2023]

Every monadically stable class, that admits sparse neighborhood covers, admits FO model checking in time $f(\varphi) \cdot |V(G)|^{11}$.

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Theorem

Every monadically stable class admits FO model checking in time $f(\varphi, \varepsilon) \cdot |V(G)|^{5+\varepsilon}$.

Roadmap: FO Model Checking for Monadically Stable Classes

flip-flatness ✓ \rightarrow flipper game ✓ \rightarrow model checking ✓

Map of the Universe

